

## Hamilton Spaces of Order $k \geq 1$

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A suitable “dual” for the  $k$ -acceleration bundle  $(T^k M, \pi^k, M)$  is the fibered bundle  $(T^{k-1}M \times_M T^*M)$ . The mentioned bundle carries a canonical presymplectic structure and  $k$  canonical Poisson structures. By means of this “dual” we define the notion of Hamilton spaces of order  $k$ , whose total space consists of points  $x$  of the configuration space  $M$ , accelerations of order  $1, \dots, k-1, y^{(1)}, \dots, y^{(k-1)}$ , and momenta  $p$ . Some remarkable Hamiltonian systems are pointed out. There exists a Legendre mapping from the Lagrange spaces of order  $k$  to the Hamilton space of order  $k$ .

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### INTRODUCTION

The notion of a Hamilton space was introduced by the author in refs. 4 and 5. It refers to a pair  $H^n = (M, H(x, p))$ , where  $M$  is a smooth  $n$ -dimensional manifold and  $H$  is a regular Hamiltonian, that is, a smooth function on the cotangent manifold  $T^*M$ , whose Hessian with respect to the momenta  $p_i$  is nonsingular. The space  $H^n$  has a canonical symplectic structure and, accordingly, a canonical Poisson structure. The regularity of the Hamiltonian  $H$  allows us to view the space  $H^n$  as the dual, via a Legendre mapping, of a Lagrange space  $L^n = (M, L(x, y))$  [1, 5, 8, 10].

The notion of Lagrange space of higher order  $k \geq 1$ ,  $L^{(k)n} = (M, L)$ , was defined some years ago [7],  $L$  being a regular Lagrangian of order  $k$ . But up to now no definition for the notion of higher order Hamilton space has been proposed. The reason is that it is not simple to find a *dual* of a Lagrange space of order  $k$ ,  $L^{(k)n}$ . Here, duality is not algebraic, but refers to the existence of a local diffeomorphism (a Legendre mapping) between two spaces.

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In the present paper we propose a suitable “dual” of the  $k$ -acceleration bundle  $T^kM$ . This is the fibered bundle  $T^{k-1}TM \times_M T^*M$  over  $M$ . We show that the total space of the latter has a canonical presymplectic structure as well as  $k$  canonical Poisson structures. Thus the notion of a higher order Hamiltonian space appears in a natural way. It is a pair  $H^{(k)n} = (M, H)$ , where  $H: T^{k-1}LM \times_M T^*M \rightarrow R$  is a regular Hamiltonian depending on the point  $x \in M$ , the accelerations of order  $1, 2, \dots, k-1, y^{(1)}, \dots, y^{(k-1)}$ , and the momenta  $p \in T^*M$ . The spaces  $H^{(k)n}$  have the following important properties:

- (a)  $\dim H^{(k)n} = \dim L^{(k)n}$ .
- (b)  $H^{(k)n}$  has a canonical presymplectic structure and a number  $k$  of canonical Poisson structures.
- (c) The spaces  $H^{(k)n}$  and  $L^{(k)n}$  are local diffeomorphic, via a Legendre transformation.

Of course, these properties hold in the case  $k = 1$ . The geometry of the Hamilton spaces of order  $k \geq 1$  is a natural extension of the geometry of Hamilton spaces  $H^n = (M, H(x, p))$ .

## 1. THE DUAL OF THE $k$ -OSCULATING BUNDLE

Let  $M$  be a real,  $C^\infty$ -differentiable manifold  $M$  of dimension  $n$  and  $(TM, \pi, M)$ ,  $(T^*M, \pi^*, M)$  its tangent and cotangent bundle, respectively. We consider the bundle of accelerations of order  $k$ ,  $(T^kM, \pi^k, M)$ , which is identified with the osculating bundle of order  $k$ ,  $(Osc^kM, \pi^k, M)$  [8]. The points  $u \in Osc^kM$  are of the form  $u = (x, y^{(1)}, \dots, y^{(k)})$  with the canonical coordinates  $(x^i, y^{(1)i}, \dots, y^{(k)i})$ . Latin indices  $i, j, k, \dots$  run over the set  $\{1, 2, \dots, n\}$ , and the summation convention will be used.

For the bundles  $(Osc^{k-1}M, \pi^{k-1}, M)$  and  $(T^*M, \pi^*, M)$  the fibered product

$$(Osc^{k-1}M \times_M T^*M, \pi^{*k}, M) \quad (1.1)$$

can be considered. The projection  $\pi^{*k}: Osc^{*k}M \rightarrow M$ , where  $Osc^{*k}M = Osc^{k-1}M \times_M T^*M$ , is given by  $\pi^{*k}(x, y^{(1)}, \dots, y^{(k-1)}, p) = x$ . The points  $(x, p)$  belong to the manifold  $T^*M$  and their local coordinate are  $(x^i, p_i)$ .

Thus, a point  $u = (x, y^{(1)}, \dots, y^{(k-1)}, p) \in Osc^{*k}M$  consists of a point  $x$ , accelerations  $y^{(1)}, \dots, y^{(k-1)}$  of order  $1, \dots, k-1$ , and a momentum  $p$  (using terms from analytical mechanics).

The manifold  $Osc^{*k}M$  will be called the “dual space” of the total space of the  $k$ -osculating bundle  $Osc^kM$ . We say that  $Osc^kM$  and  $Osc^{*k}M$  are dual to each other since between them there exists a local Legendre diffeomorphism. In this sense and not in an algebraic one, we say that the bundle  $(Osc^{*k}M,$

$\pi^{*k}, M$ ) is dual to the bundle  $(Osc^k, \pi^k, M)$ . For  $k = 1$ ,  $(Osc^{*1}M, \pi^{*1}, M)$  is identified with the cotangent bundle  $(T^*M, \pi^*, M)$ .

The following diagram, where the arrows indicate natural projections, is commutative:

$$\begin{array}{ccccc}
 & & Osc^{*k}M & & \\
 & \swarrow & & \searrow & \\
 Osc^{*k-1}M & & \downarrow & & T^*M \\
 & \searrow & & \swarrow & \\
 & & M & & 
 \end{array}$$

A change of local coordintes on the manifold  $Osc^{*k}M$  is given by

$$\begin{aligned}
 \tilde{x}^i &= \bar{x}^i(x^1, \dots, x^n), \quad \det\left(\frac{\partial \tilde{x}^i}{\partial x^j}\right) \neq 0 \\
 \tilde{y}^{(1)i} &= \frac{\partial \tilde{x}^i}{\partial x^j} y^j \\
 \dots (k-1)\tilde{y}^{(k-1)i} &= \frac{\partial \tilde{y}^{(k-2)i}}{\partial x^j} y^{(1)j} + \dots + (k-1) \frac{\partial \tilde{y}^{(k-2)i}}{\partial y^{(k-2)j}} y^{(k-1)j} \quad (1.2) \\
 \tilde{p}_i &= \frac{\partial x^j}{\partial \tilde{x}^i} p_j
 \end{aligned}$$

and the following identities hold [7]:

$$\frac{\partial \tilde{y}^{(\alpha)i}}{\partial x^j} = \frac{\partial \tilde{y}^{(\alpha+1)i}}{\partial y^{(1)j}} = \dots = \frac{\partial \tilde{y}^{(k-1)i}}{\partial y^{(k-1-\alpha)j}}; \quad \alpha = 0, \dots, k-2; \quad y^{(0)} = x \quad (1.2')$$

Using formulas (1.2), we can introduce the following differential forms on the manifold  $Osc^{*k}M$ :

$$\begin{aligned}
 \omega &= p_i dx^i \\
 \theta &= d\omega = dp_i \wedge dx^i
 \end{aligned} \quad (1.3)$$

From (1.2) it follows that  $\tilde{p}_i d\tilde{x}_i = p_i dx^i$ . Thus the following assertions are clear.

*Theorem 1.1.*

1. The forms  $\omega$  and  $\theta$  are globally defined on  $Osc^{*k}M$ .
2.  $d\theta = 0$ ,  $\text{rank}|\theta| = 2n$ .
3.  $\theta$  is a canonical presymplectic structure on the manifold  $Osc^{*k}M$ .

Let us consider the systems of Poisson brackets: for any  $f, g \in \mathcal{F}(Osc^{*k}M)$ ,

$$\{f, g\}_\alpha = \frac{\partial f}{\partial y^{(\alpha)i}} \frac{\partial g}{\partial p_i} - \frac{\partial g}{\partial y^{(\alpha)i}} \frac{\partial f}{\partial p_i}, \quad \alpha = 0, 1, \dots, k-1; \quad y^{(0)} = x \quad (1.4)$$

*Theorem 1.2.* Every bracket  $\{\cdot\}_\alpha$  ( $\alpha = 0, \dots, k-1$ ) defines a canonical Poisson structure on the manifold  $Osc^{*k}M$ .

*Proof.* First, it is not difficult to see that for  $\alpha = 0, 1, \dots, k-1$ ,  $\{f, g\}_\alpha \in \mathcal{F}(Osc^{*k}M)$  and  $\{\tilde{f}, \tilde{g}\}_\alpha = \{f, g\}_\alpha$ .

Indeed, by means of (1.2) we have

$$\begin{aligned} \frac{\partial f}{\partial y^{(\alpha)i}} &= \frac{\partial \tilde{y}^{(\alpha)m}}{\partial y^{(\alpha)i}} \frac{\partial \tilde{f}}{\partial \tilde{y}^{(\alpha)m}} + \frac{\partial \tilde{y}^{(\alpha+1)m}}{\partial y^{(\alpha)i}} \frac{\partial \tilde{f}}{\partial \tilde{y}^{(\alpha+1)m}} + \dots \\ &\quad + \frac{\partial \tilde{y}^{(k-1)m}}{\partial y^{(\alpha)i}} \frac{\partial \tilde{f}}{\partial \tilde{y}^{(k-1)m}} + \frac{\partial \tilde{p}_m}{\partial y^{(\alpha)i}} \frac{\partial \tilde{f}}{\partial \tilde{p}_m} \\ \frac{\partial g}{\partial p_i} &= \frac{\partial x^i}{\partial \tilde{x}^s} \frac{\partial \tilde{g}}{\partial \tilde{p}_s} \end{aligned}$$

Using (1.2'), we can write first of the previous formulas as

$$\begin{aligned} \frac{\partial f}{\partial y^{(\alpha)i}} &= \frac{\partial \tilde{x}^m}{\partial x^i} \frac{\partial \tilde{f}}{\partial \tilde{y}^{(\alpha)m}} + \frac{\partial \tilde{y}^{(1)m}}{\partial x^i} \frac{\partial \tilde{f}}{\partial \tilde{y}^{(\alpha+1)m}} + \dots \\ &\quad + \frac{\partial \tilde{y}^{(k-1-\alpha)m}}{\partial x^i} \frac{\partial \tilde{f}}{\partial \tilde{y}^{(k-1)m}} + \frac{\partial \tilde{p}_m}{\partial y^{(\alpha)i}} \frac{\partial \tilde{f}}{\partial \tilde{p}_m} \end{aligned}$$

Now, taking into account the identities

$$\begin{aligned} \frac{\partial \tilde{p}_m}{\partial y^{(\alpha)i}} &= 0 \quad \text{for } \alpha \neq 0, & \frac{\partial \tilde{p}_m}{\partial x^i} \frac{\partial x^i}{\partial \tilde{x}^s} &= 0 \\ \frac{\partial \tilde{y}^{(\beta)m}}{\partial x^i} \frac{\partial x^i}{\partial \tilde{x}^s} &= \frac{\partial \tilde{y}^{(\beta)m}}{\partial \tilde{x}^s} = 0 & \text{for } \beta &= 1, 2, \dots, k-1 \end{aligned}$$

we obtain

$$\frac{\partial f}{\partial y^{(\alpha)i}} \frac{\partial g}{\partial p_i} = \frac{\partial \tilde{f}}{\partial \tilde{y}^{(\alpha)i}} \frac{\partial \tilde{g}}{\partial \tilde{p}_i}, \quad \text{for } \alpha = 0, \dots, k-1; \quad y(0) = x$$

Consequently,

$$\{f, g\}_\alpha = \{\tilde{f}, \tilde{g}\}_\alpha$$

Now it is not difficult to prove that the brackets  $\{f, g\}_\alpha$  (i) are R-linear in every argument, (ii) are skew-symmetric:  $\{f, g\}_\alpha = -\{g, f\}_\alpha$ , and (iii) satisfy the Jacobi identities

$$\{\{f, g\}_\alpha, h\}_\alpha + \{\{g, h\}_\alpha, f\}_\alpha + \{\{h, f\}_\alpha, g\}_\alpha = 0, \quad \alpha = 0, 1, \dots, k - 1$$

and the mapping  $\{f, \cdot\}_\alpha: \mathcal{F}(Osc^{*k}M) \rightarrow \mathcal{F}(Osc^{*k}M)$  is a derivation of the functions algebra  $\mathcal{F}(Osc^{*k}M)$ .

The previous theorems allow us to study Hamiltonian systems over the manifold  $Osc^{*k}M$ .

## 2. THE HAMILTONIAN SYSTEMS OF ORDER $k$

As usual [7], we set  $\tilde{O}sc^{*k}M = Osc^{*k}M \setminus \{0\}$ , where 0 means the zero section of the projection  $\pi^{*k}$ .

*Definition 2.1.* A mapping  $H: Osc^{*k}M \rightarrow R$  is called a *differentiable Hamiltonian of order  $k$*  if  $H$  is a differentiable function on  $\tilde{O}sc^{*k}M$ , and it is continuous on the zero section.

Thus, if  $H(u) = H(x, y^{(1)}, \dots, y^{(k-1)}, p)$  is a function of the particle  $x$ , the accelerations of order  $1, 2, \dots, k - 1$ , and the momenta  $p_i$ , it will be a differentiable Hamiltonian of order  $k$  if this function is differentiable on the manifold  $\tilde{O}sc^{*k}M$ ; it is continuous at the points  $(x, 0, \dots, 0, 0)$ .

*Definition 2.2.* A Hamiltonian system of order  $k$  is a triple  $(Osc^{*k}M, \theta, H)$ , where  $\theta$  is a presymplectic structure on  $Osc^{*k}M$  and  $H$  is a differentiable Hamiltonian on the manifold  $Osc^{*k}M$ .

In the particular case  $k = 1$ , where  $\theta$  is the canonical symplectic structure over  $T^*M$ , we have the classical Hamiltonian systems.

If  $\theta$  is the presymplectic structure on  $Osc^{*k}M$  given by (1.3.) and  $H$  is a differentiable Hamiltonian on  $Osc^{*k}M$ , we obtain an important Hamiltonian system, which can be studied by a method of Gotay [2]. In this case, the Poisson structure  $\{\cdot\}_0$  will be considered. We follow here another way [11,12], introducing  $k$ -induced Hamiltonian systems  $\{E_\alpha, \theta_\alpha, H_\alpha\}$  ( $\alpha = 0, 1, \dots, k - 1$ ) as follows.

Let us consider the section  $\Sigma_0$  of the projection  $Osc^{*k}M \rightarrow T^*M$  (from the above diagram), defined by

$$\Sigma_0 = \{(x, y^{(1)}, \dots, y^{(k-1)}, p) \in Osc^{*k}M \mid y^{(1)} = \dots = y^{(k-1)} = 0\}.$$

It is an immersed submanifold of the manifold  $Osc^{*k}M$ . We denote by  $H_0$  the restriction to  $\Sigma_0$  of a differentiable Hamiltonian  $H$  on  $Osc^{*k}M$  and by  $\theta_0$  the restriction of the 2-form  $\theta$  of (1.3). Of course,  $\dim \Sigma_0 = 2n$ ,  $\theta_0$  is a canonical symplectic structure, and  $H_0$  is a differentiable Hamiltonian on  $\Sigma_0$ . Consequently, the triple  $(\Sigma_0, \theta_0, H_0)$  is a Hamiltonian system.

Now, we can prove the following:

*Theorem 2.1:*

1. The triple  $(\Sigma_0, \theta_0, H_0)$  is a Hamiltonian system,  $\theta_0$  being a symplectic structure on  $\Sigma_0$ .

2. There exists a unique vector field  $X_{H_0}$  determined by the equation

$$i_{X_{H_0}}\theta_0 = -dH_0 \quad (2.1)$$

3. The integral curves of the vector field  $X_{H_0}$  are given by the canonical equations

$$\frac{dx^i}{dt} = \frac{\partial H_0}{\partial p_i}, \quad \frac{dp_i}{dt} = -\frac{\partial H_0}{\partial x^i} \quad (\text{on } \Sigma_0) \quad (2.2)$$

4. The following equation holds:

$$\{f, g\}_0 = \theta_0(X_f, X_g) \quad \forall f, g \in \mathcal{F}(\Sigma_0) \quad (2.3)$$

where  $\{f, g\}_0$  is the Poisson structure, (1.4).

The previous result is also valid for the Poisson structure  $\{\cdot\}_\alpha$  ( $\alpha = 1, \dots, k-1$ ).

Indeed, let  $\Sigma_\alpha$  be the immersed submanifold of the fiber  $(\pi^{*k})^{-1}(x_0) \subset \text{Osc}^{*k}M$  in a fixed point  $x_0 \in M$ . Then  $\Sigma_\alpha$  is defined by

$$\begin{aligned} \Sigma_\alpha &= \{(x, y^{(1)}, y^{(2)}, \dots, y^{(k-1)}, p) \\ &\in \text{Osc}^{*k}M \mid (x = x_0, y^{(\beta)} = 0, \beta \neq \alpha, y^{(\alpha)} = y^{(\alpha)}, p = p) \\ &(\alpha = 1, \dots, k-1)\} \end{aligned} \quad (2.4)$$

Consequently, Theorem 2.1 can be proved for the Hamiltonian systems  $(\Sigma_\alpha, \theta_\alpha, H_\alpha)$  where  $H_\alpha$  is the restriction of the differentiable Hamiltonian  $H(x, y^{(1)}, \dots, y^{(k-1)}, p)$  to the submanifold  $\Sigma_\alpha$  and

$$\theta_\alpha = dp_i \wedge dy^{(\alpha)i}, \quad \alpha = 1, \dots, k-1 \quad (2.5)$$

Obviously, denoting

$$\omega_\alpha = p_i dy^{(\alpha)i} \quad \alpha = 1, \dots, k-1$$

we have  $k-1$  1-forms, every one being defined on the submanifold  $\Sigma_\alpha$ . It follows that  $\theta_\alpha = d\omega_\alpha$  ( $\alpha = 1, \dots, k-1$ ).

As in the previous theorem, we have the following result:

*Theorem 2.2:*

1. For each  $(\alpha = 1, \dots, k-1)$ , the triple  $(\Sigma_\alpha, \theta_\alpha, H_\alpha)$  is a Hamiltonian system,  $\theta_\alpha$  given by (1.4) being a symplectic structure on the submanifold  $\Sigma_\alpha$ .

2. There exists a unique vector field  $X_{H_\alpha}$  determined by the equation

$$i_{X_{H_\alpha}} \theta_\alpha = -dH_\alpha \tag{2.6}$$

3. The integral curves of the vector field  $X_{H_\alpha}$  are the “canonical equations”

$$\frac{dy^{(\alpha)i}}{dt} = \frac{\partial H_\alpha}{\partial p_i}, \quad \frac{dp_i}{dt} = -\frac{\partial H_\alpha}{\partial y^{(\alpha)i}} \quad (\text{on } \Sigma_\alpha) \tag{2.7}$$

4. The following equation holds:

$$\{f, g\}_\alpha = \theta_\alpha(X_f, X_g) \quad \forall f, g \in \mathcal{F}(\Sigma_\alpha) \tag{2.8}$$

$\{f, g\}_\alpha$  ( $\alpha = 1, \dots, k - 1$ ) being given by the Poisson structures (1.4).

Of course, this theory is valid in the case when the differentiable Hamiltonian of order  $k$ ,  $H$ , is regular.

### 3. THE NOTION OF HAMILTON SPACE OF ORDER $k$

The Hessian matrix of a differentiable Hamiltonian of order  $k$ ,  $H(x, y^{(1)}, \dots, y^{(k-1)}, p)$  with respect to the momenta  $p_i$ , has the entries

$$g^{ij} = \frac{1}{2} \frac{\partial^2 H}{\partial p_i \partial p_j} \quad \text{on } \tilde{Osc}^{*k}M \tag{3.1}$$

We can prove without difficulty that  $g^{ij}$  is a distinguished contravariant symmetric tensor field.

We say that  $H$  is regular if

$$\text{rank } \|g^{ij}\| = n = \dim M, \quad \text{on } \tilde{Osc}^{*k}M \tag{3.1'}$$

*Definition 3.1.* A Hamilton space of order  $k$  ( $k \in \mathbb{N}^*$ ) is a pair  $H^{(k)n} = (M, H(x, y^{(1)}, \dots, y^{(k-1)}, p))$  formed by a smooth, real,  $n$ -dimensional manifold  $M$  and a differentiable regular Hamiltonian  $H$  of order  $k$ , for which the  $d$ -tensor field  $g^{ij}$  has a constant signature on  $Osc^{*k}M$ .

It is easy to prove the following:

*Theorem 3.1.* If the base manifold  $M$  is paracompact, then on the manifold  $Osc^{*k}M$  there exist Hamiltonians  $H$  such that the pairs  $(M, H)$  are Hamilton spaces of order  $k$ .

*Example.* Let  $F^{(k-1)n} = (M, F(x, y^{(1)}, \dots, y^{(k-1)}))$  be a Finsler space of order  $k - 1$  [8].  $F$  exists if  $M$  is a paracompact manifold. If  $a_{ij}(x, y^{(1)}, \dots, y^{(k-1)})$  is the fundamental tensor field of the space  $F^{(k-1)n}$ , then

$$H(x, y^{(1)}, \dots, y^{(k-1)}, p) = a^{ij}(x, y^{(1)}, \dots, y^{(k-1)})p_i p_j \tag{3.2}$$

where  $a^{ij}$  is the contravariant tensor associated with  $a_{ij}$ , is the fundamental function of a Hamilton space of order  $k$ .

For a Hamilton space  $H^{(k)n} = (M, H)$ ,  $H$  is called the fundamental function and  $g^{ij}$  its fundamental tensor field.

The geometry of the Hamilton spaces of order  $k$  can be studied as a natural extension of the geometry of Hamilton space of order 1 [1, 4, 5, 10]. Some special classes of spaces  $H^{(k)n}$  are as follows.

1. The Riemannian spaces  $H^{(k)n} = (M, H)$  defined as spaces  $H^{(k)n}$  for which the fundamental function  $H(x, y^{(1)}, \dots, y^{(k-1)}, p)$  is 2-homogeneous with respect to  $p_i$  and its fundamental tensor field  $g^{ij}$  does not depend on the variables  $p_i$ . We denote them by  $\mathcal{R}^{(k)n}$ .
2. The Cartan spaces of order  $k$  are the Hamilton spaces of order  $k$ , for which the fundamental function  $H$  is 2-homogeneous with respect to the momenta  $p_i$ . We denote them by  $\mathcal{C}^{(k)n} = (M, H(x, y^{(1)}, \dots, y^{(k-1)}, p))$ .

A more general class of spaces is given by the generalized Hamilton spaces of order  $k$ .

They are defined as pairs  $GH^{(k)n} = (M, g^{ij}(x, y^{(1)}, \dots, y^{(k-1)}, p_i))$ , where  $g^{ij}$  is a distinguished tensor fields [9] which has the properties that  $\text{rank}\|g^{ij}\| = n$  on  $\tilde{Osc}^{*k}M$  and  $g^{ij}$  has a constant signature.

*Example.* If  $\gamma^{ij}(x)$  is the contravariant tensor of the metric tensor  $\gamma_{ij}(x)$  of a Riemannian space on the manifold  $M$  and  $n(x, y^{(1)}, \dots, y^{(k-1)}, p) > 1$  is a function (refractive index) on  $Osc^{*k} M$ , then the spaces  $GH^{(k)n} = (M, g^{ij})$ , with

$$g^{ij}(x, y^{(1)}, \dots, y^{(k-1)}, p) = \gamma^{ij}(x) + \left(1 - \frac{1}{n^2(x, y^{(1)}, \dots, y^{(k-1)}, p)}\right) p^i p^j \quad (3.3)$$

where  $p^i = \gamma^{ij}(x)p_j$ , are generalized Hamilton spaces of order  $k$ .

For the space  $GH^{(k)n}$  there is no fundamental function  $H$  such that  $g^{ij} = \frac{1}{2} \partial^2 H / \partial p_i \partial p_j$ .

The spaces  $GH^{(k)n}$  were suggested by Synge's metric of relativistic optics [9].

Evidently, the previous classes of Hamilton spaces satisfy the inclusions

$$\{\mathcal{R}^{(k)n}\} \subset \{\mathcal{C}^{(k)n}\} \subset \{\mathcal{H}^{(k)n}\} \subset \{GH^{(k)n}\}$$

Similar inclusions hold for the Lagrange spaces of order  $k$  [7]:

$$\{\mathcal{R}^{(k)n}\} \subset \{F^{(k)n}\} \subset \{L^{(k)n}\} \subset \{GL^{(k)n}\}$$

where  $F^{(k)n}$  are Finsler spaces of order  $k$  [8].

The relation between the Lagrange spaces of order  $k$ ,



$$L^{(k)n} = (M, L(x, y^{(1)}, \dots, y^{(k-1)}, y^{(k)}))$$

and the Hamilton spaces of order  $k$ ,  $H^{(k)n} = (M, H(x, y^{(1)}, \dots, y^{(k-1)}, p))$ , is given by the Legendre mapping Leg:  $L^{(k)n} \rightarrow H^{(k)n}$  defined by

$$\begin{aligned} \text{Leg: } & (x, y^{(1)}, \dots, y^{(k-1)}, y^{(k)}) \\ & \in \text{Osc}^k M \rightarrow (x, y^{(1)}, \dots, y^{(k-1)}, p) \in \text{Osc}^{*k} M \end{aligned} \quad (3.4)$$

where

$$p_i = \frac{1}{2} \frac{\partial L}{\partial y^{(k)i}} \quad (3.4')$$

We have the following result:

*Theorem 3.2.* The Legendre mapping Leg given by (3.4) and (3.4') is a local diffeomorphism between the total spaces of Lagrange space  $L^{(k)n}$  and the Hamilton space  $H^{(k)n}$ .

Indeed, the determinant of the Jacobian matrix of the mapping Leg coincides with the determinant of the matrix  $\|a_{ij}\|$ , where  $a_{ij}(x, y^{(1)}, \dots, y^{(k)})$  is the fundamental tensor of the space  $L^{(k)n}$ . QED

Consequently, one can study the geometry of the Hamilton spaces of order  $k$  directly as an extension of the case  $k = 1$  and by using the Legendre transformations (3.4), (3.4') since the geometry of the spaces  $L^{(k)n}$  is known [7].

#### 4. CONCLUSIONS

The Lagrange spaces of order  $k \geq 1$ ,  $L^{(k)n} = (M, L(x, y^{(1)}, \dots, y^{(k)}))$ , are defined by the regular Lagrangians  $L$  which depend on points  $x$  of the configuration space  $M$  and accelerations  $y^{(1)}, \dots, y^{(k)}$  of order  $1, \dots, k$ , respectively [7]. The space  $L^{(k)n}$  is a natural extension of the notion of Lagrange space of order 1,  $L^n = (M, L(x, y))$ .

The problem is to construct the dual notion of Hamilton space of order  $k$ ,  $H^{(k)n} = (M, H)$ . It must have the following properties:

1.  $\dim L^{(k)n} = \dim H^{(k)n}$ .
2. On  $H^{(k)n}$  there exist a canonical presymplectic structure and a canonical Poisson structure.
3. There exists a local diffeomorphism between the total spaces of  $L^{(k)n}$  and  $H^{(k)n}$ .

The “dual space” of  $L^{(k)n}$  obtained by means of Jacobi–Ostrogradski momenta [3, 7] does not satisfy the previous strong conditions.

In the present paper this problem is solved by means of the fibered bundle (1.1), where  $(Osc^{k-1} M, \pi^{k-1}, M)$  is the  $(k - 1)$ -osculator bundle (or  $k - 1$  acceleration bundle) and  $(T^*M, \pi^*, M)$  is the cotangent bundle of the manifold  $M$ .

The main results concerning the dual of a  $k$ -osculator bundle, Hamiltonian systems of order  $k$ , and Hamilton spaces of order  $k$ , as well as the Legendre transformation, are given by Theorems 1.1, 1.2, 2.1, 2.2, and 3.2.

The geometry of the Hamilton spaces of order  $k$  is a natural extension of the known geometry of Hamilton space  $H^n = (M, H(x, p))$  taking into account the Legendre mapping (3.4), (3.4'). Applications in analytical mechanics of the higher order Lagrangians can be done starting from Examples 3.2 and 3.3.

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